Combining Theories Sharing Set Operations

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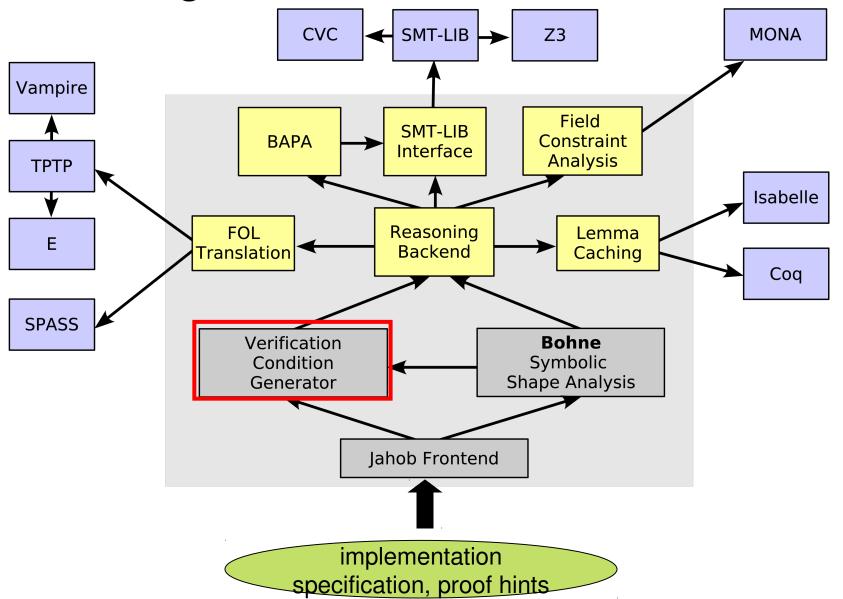
joint work with
Thomas Wies and Viktor Kuncak



Fragment of Insertion into Tree

```
class Node {Node left,right; Object data;}
class Tree {
    private static Node root;
    private static int size; /*:
    private static specvar nodes :: objset;
    vardefs "nodes==\{x. (root,x) \in \{(x,y). left x = y \lor right x = y\}^*\}";
    private static specvar content :: objset;
    vardefs "content==\{x. \exists n. n \neq null \land n \in nodes \land data n = x\}" */
    private void insertAt(Node p, Object e) /*:
      requires "tree [ left , right ] \land nodes \subseteq Object.alloc \land size = card content \land
                  e \notin content \land e \neq null \land p \in nodes \land p \neq null \land left p = null"
      modifies nodes, content, left, right, data, size
                                                                                    root
      ensures "size = card content" */
                                                               left
                                                                         right
                                                                                    size: 6
         Node tmp = new Node();
                                                           left.
                                                                    right I data
         tmp.data = e;
         p. left = tmp;
                                                     left
         size = size + 1;
                                                        data
                                                                     data
                                              data
```

Program Verification with Jahob



Generated Verification Condition

```
\neg next0^*(root0,n) \land x \notin \{data0(v) \mid next0^*(root0,v)\} \land \\ next=next0[n:=root0] \land data=data0[n:=x] \xrightarrow{} \\ |\{data(v) \cdot next^*(n,v)\}| = \\ |\{data0(v) \cdot next0^*(root0,v)\}| + 1
```

"The number of stored objects has increased by one."

Expressing this VC requires a rich logic

- transitive closure * (in lists and also in trees)
- unconstraint functions (data, data0)
- cardinality operator on sets | ... |

Is there a decidable logic containing all this?

Outline

I. Idea of decision procedure: reduction to a shared theory of sets

II. BAPA-reducible theories

III. BAPA-reduction for WS1S

Decomposing the Formula

Consider a (simpler) formula

$$|\{data(x). next*(root,x)\}| = k+1$$

Introduce fresh variables denoting sets:

```
A = \{x. next^*(root,x)\} \land \qquad 1) WS2S
B = \{y. \exists x. data(x,y) \land x \in A\} \land \qquad 2) C^2
|B|=k+1 \qquad 3) BAPA
```

Good news: conjuncts are in decidable fragments Bad news: conjuncts share more than just equality (they share set variables and set operations)

Next: explain these decidable fragments

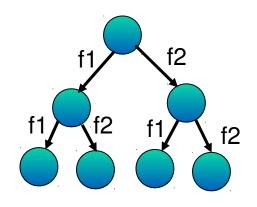
WS2S: Monadic 2rd Order Logic

Weak Monadic 2rd-order Logic of 2 Successors

$$F ::= x=f1(y) \mid x=f2(y) \mid$$

$$x \in S \mid S \subseteq T \mid \exists S.F \mid$$

$$F_1 \not E F_2 \mid \neg F$$



- quantification is over finite sets of positions in a tree
- transitive closure encoded using set quantification

Decision procedure using tree automata (e.g. MONA)

C2: Two-Variable Logic w/ Counting

Two-Variable Logic with Counting

$$F ::= P(V_1,...,V_n) \mid F_1 \not\in F_2 \mid \neg F \mid \exists^{cont} \ V_i \cdot F$$

where

P: is a predicate symbol

 v_i : is one of the **two** variable names x,y

cont : is =k, $\le k$, or $\ge k$ for nonnegative *constants* k

We can write $(\exists \le k v_i.F)$ as $|\{v_i.F\}| \le k$

We can define $\exists \forall$ and axiomatize total functions: $\forall x \exists \forall y . R(x,y)$

Decidable sat. and fin-sat. (1997), NEXPTIME even for binary-encoded k: Pratt-Hartman '05

BAPA (Kuncak et al. CADE'05): Boolean Algebra with Presburger Arithmetic

$$S ::= V \mid S_1 \cup S_2 \mid S_1 \land S_2 \mid S_1 \setminus S_2$$

$$T ::= k \mid C \mid T_1 + T_2 \mid T_1 - T_2 \mid C \cdot T \mid |S|$$

$$A ::= S_1 = S_2 \mid S_1 \subseteq S_2 \mid T_1 = T_2 \mid T_1 < T_2$$

 $F ::= A \mid F_1 \not E F_2 \mid F_1 \not C F_2 \mid \neg F \mid \exists S.F \mid \exists k.F$ BAPA decidable in alternating time (V. Kuncak et al. JAR'06), QFBAPA decidable in NP (V. Kuncak et al. CADE'07)

Also decidable: qf fragment of multisets w/ cardinalities (R. Piskac and V. Kuncak VMCAI'08,CAV'08,CSL'08)

New: role of BAPA in combination of theories sharing sets

Combining Theories by Reduction

Satisfiability problem expressed in HOL: (all free symbols existentially quantified)

```
\exists next,data,k,root. \existsA,B.

A = \{x. \text{ next}^*(\text{root},x)\} \land 1) WS2S

B = \{y. \exists x. \text{ data}(x,y) \land x \in A\} \land 2) C<sup>2</sup>

|B|=k+1 3) BAPA
```

We assume formulas share only:

- set variables (sets of uninterpreted elems)
- individual variables, as a special case {x}

Combining Theories by Reduction

Satisfiability problem expressed in HOL, after moving fragment-specific quantifiers

```
∃ A,B.

∃ next,root. A = {x. next*(root,x)} ∧

∃ data. B = {y. ∃ x. data(x,y) ∧ x ∈ A} ∧

∃ k. |B|=k+1 — F_{BAPA}
```

Extend decision procedures for fragments into

projection procedures that reduce each conjunct to a decidable shared theory applies to all non-set variables

Combining Theories by Reduction

Satisfiability problem expressed in HOL, after moving fragment-specific quantifiers

```
\exists A,B.
\exists next,root. A = \{x. next^*(root,x)\} \land
\exists data. B = \{y. \exists x. data(x,y) \land x \in A\} \land
\exists k. |B| = k+1 - F_{BAPA}
```

Check satisfiability of conjunction of projections

$$\exists A,B.F_{WSS}$$
 Æ F_{C2} Æ F_{BAPA}

Conjunction of projections satisfiable → so is original formula

Decision Procedure for Combination

- Separate formula into WS2S, C², BAPA parts
- For each part, compute projection onto set vars
- Check satisfiability of conjunction of projections

What is the right target theory for expressing the projections onto set variables?

Outline

I. Idea of decision procedure: reduction to a shared theory of sets

II. BAPA-reducible theories

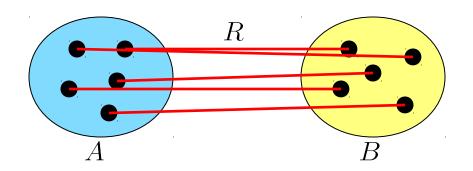
III. BAPA-reduction of WS1S

Reduction to BAPA

Consider the C² formula

$$F \equiv (\forall x. \exists^{=1} y. R(x, y)) \land (\forall x. \exists^{=1} y. R(y, x)) \land (\forall x. A(x) \leftrightarrow (\exists y. B(y) \land R(x, y)))$$

F expresses "R is bijection between A and B"



Projection of F onto A and B gives

$$(\exists R.F) \equiv (|A| = |B|)$$

Cardinalities are needed to express projections → BAPA

BAPA-Reducibility

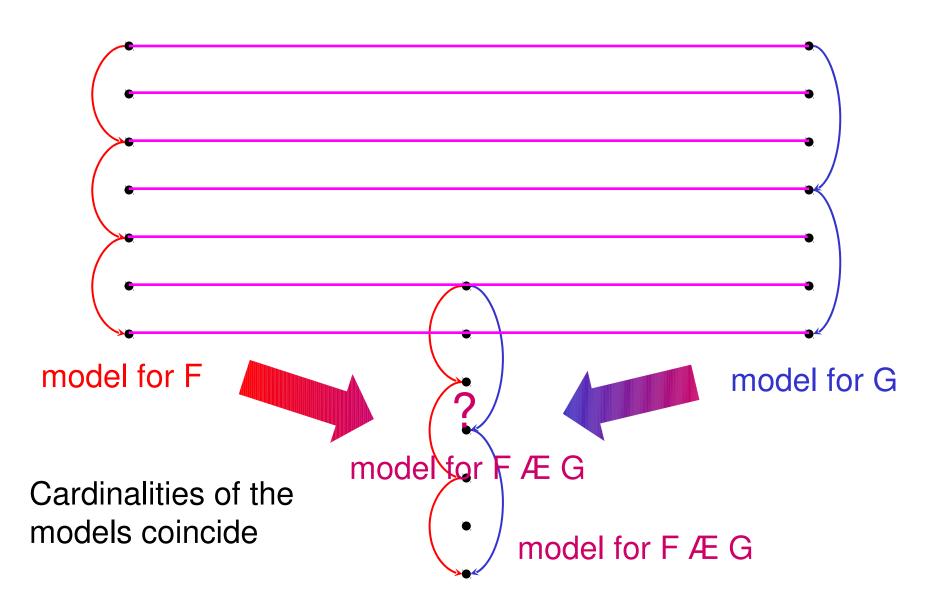
Definition: Logic is **BAPA-reducible** iff there is an algorithm that computes projections of formulas onto set variables, and these projections are BAPA formulas.

Theorem:

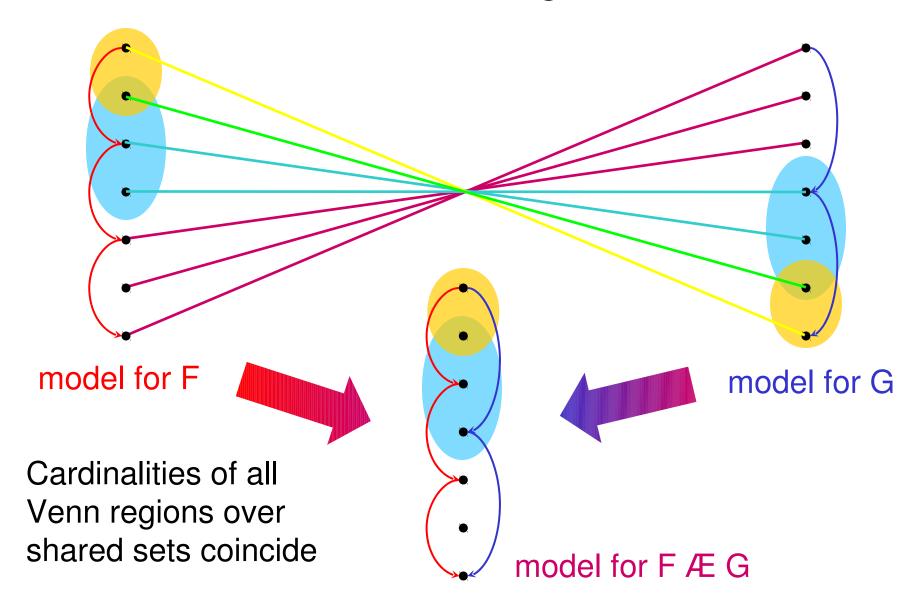
1) WS2S, 2) C², 3) BAPA, 4) BSR, 5) qf-multisets are all BAPA-reducible.

Thus, their set-sharing combination is decidable.

Amalgamation of Models: The Disjoint Case



Amalgamation of Models: The Set-Sharing Case



BAPA-reducible Theories

For a set of formulas \mathcal{F} the following are equivalent:

- theory $\mathcal{T} \subseteq \mathcal{F}$ is **BAPA-reducible**
- for every $F \in \mathcal{F}$ the set of vectors

$$\mathcal{V}(\mathcal{T}, F) = \{(|M(V_1)|, \dots, |M(V_n)|) \mid M \models \mathcal{T} \cup \{F\}\}$$

is semilinear and effectively computable, where the $M(V_i)$ are the Venn regions over the free set variables of F in its \mathcal{T} -models M

Projections onto the set variables characterize the sets $\mathcal{V}(\mathcal{T}, F)$.

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III. BAPA-reduction of WS1S

WS1S formula for a regular language

$$F = ((A \cancel{E} \neg B)(B \cancel{E} \neg A))^* (\neg B \cancel{E} \neg A)^*$$

Formulas are interpreted over finite words

Symbols in alphabet correspond to $(\neg A \not E \neg B), (A \not E \neg B), (\neg A \not E B), (A \not E B)$

Model of formula F

WS1S formula for a regular language

$$F = ((A \cancel{E} \neg B)(B \cancel{E} \neg A))^* (\neg B \cancel{E} \neg A)^*$$

Model of formula F

A,B denote sets of positions in the word w.

Parikh image gives card.s of Venn regions

Parikh(w) =
$$\{ 00 \square 7, 10 \square 4, \square 4, \square 4 \}$$

Decision procedure for sat. of WS1S:

- construct finite word automaton A from F
- check emptiness of L(A)

Parikh 1966:

Parikh image of a regular language is semilinear and effectively computable from the finite automaton

Construct BAPA formula from Parikh image of the reg. lang.

WS1S formula for a regular language

$$F = ((A \cancel{E} \neg B)(B \cancel{E} \neg A))^* (\neg B \cancel{E} \neg A)^*$$

Parikh image of the models of F:

Parikh(F) =
$$\{(q,p,p,0) \mid q,p \ge 0\}$$

BAPA formula for projection of F onto A,B: $|A \mathring{A} B^c| = |A^c \mathring{A} B| \not E |A \mathring{A} B| = 0$

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class Node {Node left,right; Object data;}
class Tree {
    private static Node root;
    private static int size; /*:
    private static specvar nodes :: objset;
    vardefs "nodes==\{x. (root,x) \in \{(x,y). left x = y \lor right x = y\}^*\}";
    private static specvar content :: objset;
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    private void insertAt(Node p, Object e) /*:
      requires "tree [ left , right ] \land nodes \subseteq Object.alloc \land size = card content \land
                  e \notin content \land e \neq null \land p \in nodes \land p \neq null \land left p = null
      modifies nodes, content, left, right, data, size
      ensures "size = card content" */
                                                                         right
                                                                                 size: 6
                                                               left
         Node tmp = new Node();
                                                           left.
                                                                    right I data
         tmp.data = e;
         p. left = tmp;
                                                     left
         size = size + 1;
                                                        data
                                                                     data
                                              data,
```

Reduction of VC for insertAt

```
SHARED SETS: nodes, nodes1, content, content1, {e}, {tmp}
WS2S FRAGMENT:
 tree [ left , right ] \land left p = null \land p \in nodes \land left tmp = null \land right tmp = null \land
 nodes=\{x. (root,x) \in \{(x,y). left x = y | right x = y\}^*\} \land
 nodes1=\{x. (root,x) \in \{(x,y). (left (p:=tmp)) | x = y\}
CONSEQUENCE: nodes1=nodes ∪ {tmp}
C2 FRAGMENT:
  data tmp = null \land (\forall y. data y \neq tmp) \land tmp \notin alloc \land nodes \subseteq alloc \land
  content=\{x. \exists n. n \neq null \land n \in nodes \land data n = x\} \land
  content1 = \{x. \ \exists \ n. \ n \neq null \ \land \ n \in nodes1 \ \land \ (data(tmp:=e)) \ n = x\}
CONSEQUENCE: nodes 1 \neq \text{nodes} \cup \{\text{tmp}\} \vee \text{content} = \text{content} \cup \{\text{e}\}
BAPA FRAGMENT: e ∉ content ∧ card content1 ≠ card content + 1
CONSEQUENCE: e ∉ content ∧ card content1 ≠ card content + 1
```

Conjunction of projections unsatisfiable → so is original formula

Related Work on Combination

- Nelson-Oppen, 1980 disjoint theories reduces to equality logic (finite # of formulas)
- Tinelli, Ringeissen, 2003 general non-disjoint we consider the particular case of sets
- Ghilardi sharing locally finite theories cardinality on sets needed, not locally finite
- Fontaine gentle theories (BSR, ...) disjoint case only
- Ruess, Klaedtke WS2S + cardinality (no C2)
- Reduction procedures to SAT (UCLID)
 - we reduce to (QF)BAPA (NP-complete) reduction QFBAPA → QFPA → SAT non-trivial

Summary

Presented new combination technique for theories sharing sets by reduction to a common shared theory (BAPA).

Identified an expressive decidable set-sharing combination of theories by extending their decision procedures to BAPA-reductions

1) WS2S, 2) C2 3) BSR, 4) BAPA, 5) qf-multisets

Resulting theory is useful for automated verification of complex properties of data structure implementations.