

Automated Proving in Geometry using Gröbner bases in Isabelle/HOL

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and Applications

Outline

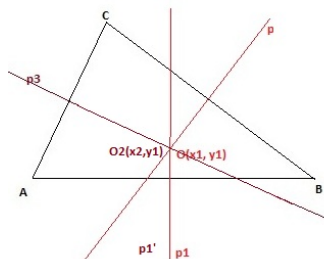
- 1 Motivation example
- 2 Term representation of geometry constructions
- 3 Algorithm
- 4 Conclusion and future work

Outline

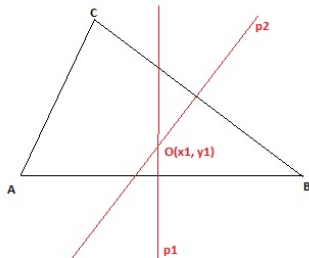
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Motivation example

- The goal is to show that bisectors of the sides of triangle are intersecting in one point

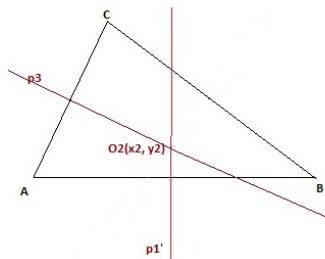


Motivation example



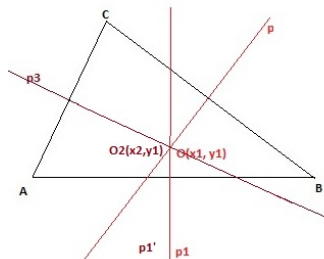
- $A(0, 0), B(0, c), C(a, b)$
- $O_1(x_1, y_1) = p_1 \cap p_2$
- $p_1 = x_1 - \frac{c}{2}$
- $p_2 = \frac{c-a}{b}x_1 - y_1 + \frac{b^2 - c^2 + a^2}{2b}$

Motivation example



- $A(0, 0), B(0, c), C(a, b)$
- $O_2(x_2, y_2) = p'_1 \cap p_3$
- $p'_1 = x_2 - \frac{c}{2}$
- $p_3 = \frac{a}{b}x_2 + y_2 - \frac{b}{2} - \frac{a^2}{2b}$

Motivation example



- $A(0, 0), B(0, c), C(a, b)$
- $O_1(x_1, y_1) = O_2(x_2, y_2)$
- $G = \left\{ x_1 - \frac{c}{2}, \frac{c-a}{b}x_1 - y_1 + \frac{b^2 - c^2 + a^2}{2b}, x_2 - \frac{c}{2}, \frac{a}{b}x_2 + y_2 - \frac{b}{2} - \frac{a^2}{2b} \right\}$

Motivation example

The problem $O_1(x_1, y_1) = O_2(x_2, y_2)$ is now to show that polynomials

$$g_1 = x_1 - x_2 \text{ and } g_2 = y_1 - y_2$$

belong to the ideal generated over the set G .

We can do that by calculating the Gröbner basis G' of the set G and showing:

$$\text{i) } g_1 = x_1 - x_2 \xrightarrow{*}_{G'} 0$$

$$\text{ii) } g_2 = y_1 - y_2 \xrightarrow{*}_{G'} 0$$

Motivation example

- New set: $G' = \{p_1, p_2, p_3, p'_1, S_1, S_2\} =$
 $\{x_1 - \frac{c}{2},$
 $\frac{c-a}{b}x_1 - y_1 + \frac{b^2-c^2+a^2}{2b},$
 $\frac{a}{b}x_2 + y_2 - \frac{b}{2} - \frac{a^2}{2b},$
 $x_2 - \frac{c}{2},$
 $-y_1 + \frac{b}{2} + \frac{a^2}{2b} - \frac{ac}{2b},$
 $y_2 - \frac{b}{2} - \frac{a^2}{2b} + \frac{ac}{2b}\}$
- We can show: $g_1 = x_1 - x_2 \xrightarrow{*}_{G'} 0$
- We can show: $g_2 = y_1 - y_2 \xrightarrow{*}_{G'} 0$

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Term representation of geometry constructions

- We use term representation for geometry constructions
- Each **object** has term representation, for example:
 - line = Line point point
 - or: line = Bisector point point
 - etc.
- Each **statement** has term representation, for example:
 - In point line
 - Equal point point
 - etc.

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Algorithm

- Term representation of our example:

```
Equal(  
Intersect(Bisector(Point 1, Point 2), Bisector(Point 2, Point 3))),  
Intersect(Bisector(Point 1, Point 2), Bisector(Point 1, Point 3)))
```

- Algorithm for making **two set of polynomials** from term representation of geometry construction
- From **the second set** we get Gröbner basis G'
- From the **first set we get polynomials** that should go to 0 by polynomial reduction with elements from G'

Algorithm

- Algorithm is recursive, for each object we add new variables and call function to read the rest of the term
- For example:
 - In `point_t` `line_t`
 - add variables `x1` i `y1` - coordinates for point (for example $O(x_1, y_1)$)
 - add variables `a1` i `b1` - coefficients for line (for example $p = a_1 \cdot x + b_1 \cdot y + 1$)
 - call `point_poly(point_t, x1, y1)`
 - call `line_poly(line_t, a1, b1)`
 - we add in first set the polynomial: $a1x1 + b1y1 + 1$
- For representing polynomials in Isabelle we use work of Christian Sternagel and Ren Thiemann - *Executable Multivariate Polynomials*

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Conclusion and future work

- Including more geometry objects
- Implementing algorithm in wider range of geometry statements to show their correctness
- Using implemented method for calculating Gröbner basis in Isabelle
- Implementing Buchberger's algorithm (with heuristics) for transforming the set of polynomials in Gröbner basis in some imperative language (for example C) and proving its correctness in Isabelle