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Motivation

- Coherent logic (CL) (also called geometric logic) is a fragment of FOL
- Good features: certain quantification allowed, direct, readable proofs, simple generation of formal proofs...
- However, existing provers for CL are still not very efficient
- SAT and SMT solvers are at rather mature stage
- However, only universal quantification is allowed; producing readable and/or formal proofs is often challenging;
- Goal: build an efficient prover for CL based on SAT/SMT



What is Coherent Logic

• CL formulae are of the form:

$$A_1(\vec{x}) \wedge \ldots \wedge A_n(\vec{x}) \Rightarrow \exists \vec{y}_1 \ B_1(\vec{x}, \vec{y}_1) \vee \ldots \vee \exists \vec{y}_m \ B_m(\vec{x}, \vec{y}_m)$$

 $(A_i \text{ are literals}, B_i \text{ are conjunctions of literals})$

- No function symbols of arity greater than 0
- The problem of deciding $\Gamma \vdash \Phi$ is semi-decidable
- First used by Skolem, recently popularized by Bezem et al.



CL Realm

- A number of theories and theorems can be formulated directly and simply in CL
- Example (Euclidean geometry theorem): for any two points there is a point between them
- Most of elementary geometry belongs to CL
- Conjectures in abstract algebra, confluence theory, lattice theory, and many more (Bezem et al)



CL Proof System

- CL has a natural proof system (natural deduction style), based on forward ground reasoning
- Existential quantifiers are eliminated by introducing witnesses
- A conjecture is kept unchanged and proved directly (refutation, Skolemization and clausal form are not used)
- CL is a suitable framework for producing readable and for producing formal proofs



ArgoCLP Prover

- Developed by Sana Stojanović, Vesna Pavlović, Predrag Janičić (2009), based on the prover Euclid (developed by Stevan Kordić and Predrag Janičić, 1995.)
- Sound and complete
- A number of techniques that increase efficiency (some of them sacrificing completeness)
- Both formal (Isabelle) and natural language proofs can be exported
- Applied primarily in geometry, proved tens of theorems



Geometry Example

Assuming that $p \neq q$, and $q \neq r$, and the line p is incident to the plane α , and the line q is incident to the plane α , and the line r is incident to the plane α , and the lines p and q do not intersect, and the lines q and r do not intersect, and the point q is incident to the plane q, and the point q is incident to the line q, and the point q is incident to the line q, show that q is incident to the line q.

p r

Generated Proof

Introduction

Let us prove that p = r by reductio ad absurdum.

- 1. Assume that $p \neq r$.
 - It holds that the point A is incident to the line q or the point A is not incident to the line q (by axiom of excluded middle).
 - 3. Assume that the point A is incident to the line q.
 - From the facts that p ≠ q, and the point A is incident to the line p, and the point A is incident to the line q, it holds that the lines p and q intersect (by axiom ax_D5).
 - From the facts that the lines p and q intersect, and the lines p and q do not intersect we get a contradiction.
 Contradiction.



Generated Proof (2)

Introduction

- 6. Assume that the point A is not incident to the line q.
 - 7. From the facts that the lines *p* and *q* do not intersect, it holds that the lines *q* and *p* do not intersect (by axiom ax_nint_l_l_21).
 - 8. From the facts that the point A is not incident to the line q, and the point A is incident to the plane α , and the line q is incident to the plane α , and the point A is incident to the line p, and the line p is incident to the plane α , and the lines q and p do not intersect, and the point A is incident to the line r, and the line r is incident to the plane α , and the lines q and r do not intersect, it holds that p = r (by axiom ax_E2).
 - 9. From the facts that p = r, and $p \neq r$ we get a contradiction. Contradiction.

Therefore, it holds that p = r.

This proves the conjecture.



CDCL-based CL Prover — ArgoCaLyPso

- Motivation: use forward-chaining with CDCL-like techniques
- In several ways similar to ArgoCLP but with a new search engine
- As the previous version, the prover is forward-chaining based, but guided by DPLL-style search procedure, uses or will use decide, backjump, learn, etc.
- Uses to some extent the architecture of ArgoSAT (by Filip Marić)
- \bullet C++, currently \approx 10000 lines of code, but not yet finished



ArgoCaLyPso and Abstract Transition System

Described in terms of abstract transition system

Instantiate:

$$\frac{A(x_1, x_2, \dots, x_i, \dots, x_n) \in F}{F := F \cup \{A(x_1, x_2, \dots, a, \dots, x_n)\}}$$

Intro:

$$\frac{\exists y.A \in F \qquad a \not\in \Sigma}{F := F \cup \{A[y \mapsto a]\}} \quad \Sigma := \Sigma \cup \{a\} \text{ where } A \text{ does not contain free universally quantified variables}$$

Resolve:

$$\frac{I_1 \vee \ldots \vee I_i \vee \ldots \vee I_n \in F \quad M \models \overline{I} \quad (I_1 \vee \ldots \vee I_{i_1} \vee I_{i+1} \vee \ldots \vee I_n) \sigma \notin F}{F := F \cup \{(I_1 \vee \ldots \vee I_{i_1} \vee I_{i+1} \vee \ldots \vee I_n) \sigma\}}$$

where σ is a most general unifier for I_i and I.



ArgoCaLyPso and Abstract Transition System

- Related to the SAT transition system by Krstić and Goel
- Properties of this system have been formally proved (by Filip Marić)
- Hopefully, ArgoCaLyPso could benefit from that proof



ArgoCaLyPso and FOL

- The trail contains FOL literals
- The axioms make the initial set of clauses
- The set of clauses can be extended by instances of existing clauses or resolvents between existing clauses and literals from the trail
- Example: if the set of clauses contains $p(x) \Rightarrow q(x) \lor r(x)$ and the trail contains p(a), then the clause $q(a) \lor r(a)$ can be added
- Existential quantifiers are eliminated by introducing witnesses



ArgoCaLyPso and Search

- One can perform DPLL-like search until all the clauses are satisfied, and then produce new clauses by instantiation, resolution or elimination of existential quantifiers
- The search on one branch is finished if \bot (as in CDCL solvers) or the conclusion of the goal formula has been reached
- When one branch is closed, all irrelevant preceding branching points are skipped in further search (backjump)



ArgoCaLyPso and Search (2)

- The rule decide can be performed on ground clauses $A_1 \vee ... \vee A_n$ (in DPLL, decide is applied on implicit clauses $p \vee \neg p$)
- Example: for three different collinear points A, B, and C one of them is between the other two
- In ArgoCaLyPso, the axiom of excluded middle is explicit, and it is not necessarily used



Some issues in prover development

- Iterative deepening and object explosion
- Rapid production of new clauses
- Constraining decide rule
- Rule ordering

- Handling equality
- Predicate symmetry
- CL formula is DNF, rather then clause



Features not implemented yet

- Lemma learning
- Export of formal proofs
- Predicate symmetry for arity greater than 2
- Guiding heuristics and implementational tricks



Preliminary experiments

Introduction

- Examples from geometry and rewriting
- Limited comparison to Vampire



Conclusions and Future Work

Related work

Introduction

- Euclid and ArgoCLP
- Marc Bezem's CL prover
- Instance based provers (Darwin)
- EPR solvers



Conclusions and Future Work

Conclusions and Future Work

- Hopefully, efficient CDCL-based CL prover
- Hopefully, acceptably efficient SAT solver
- Applications in geometry (and education)
- Applications in program synthesis

